Harnessing GPU compute with C++ Accelerated Massive Parallelism

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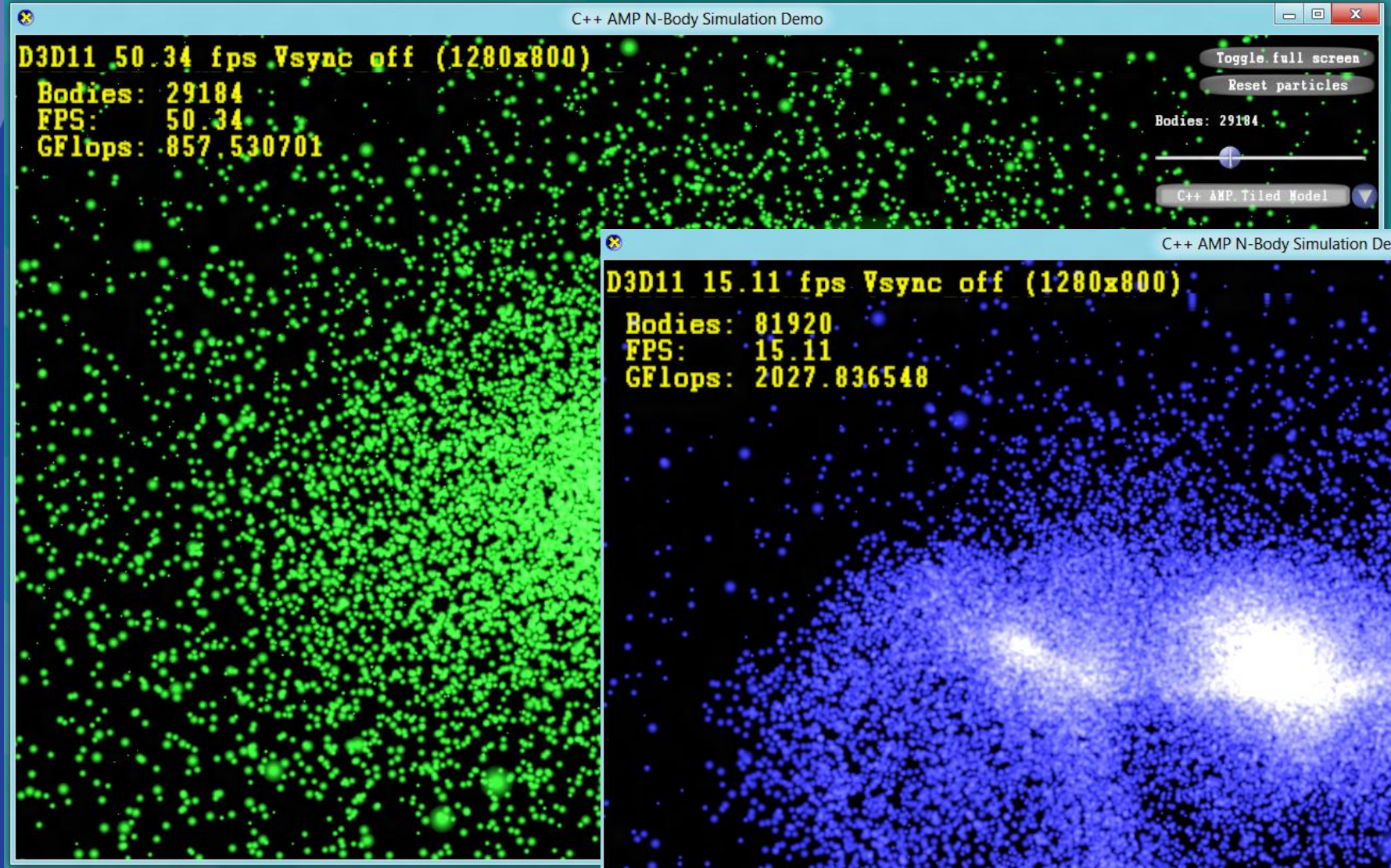
关于我

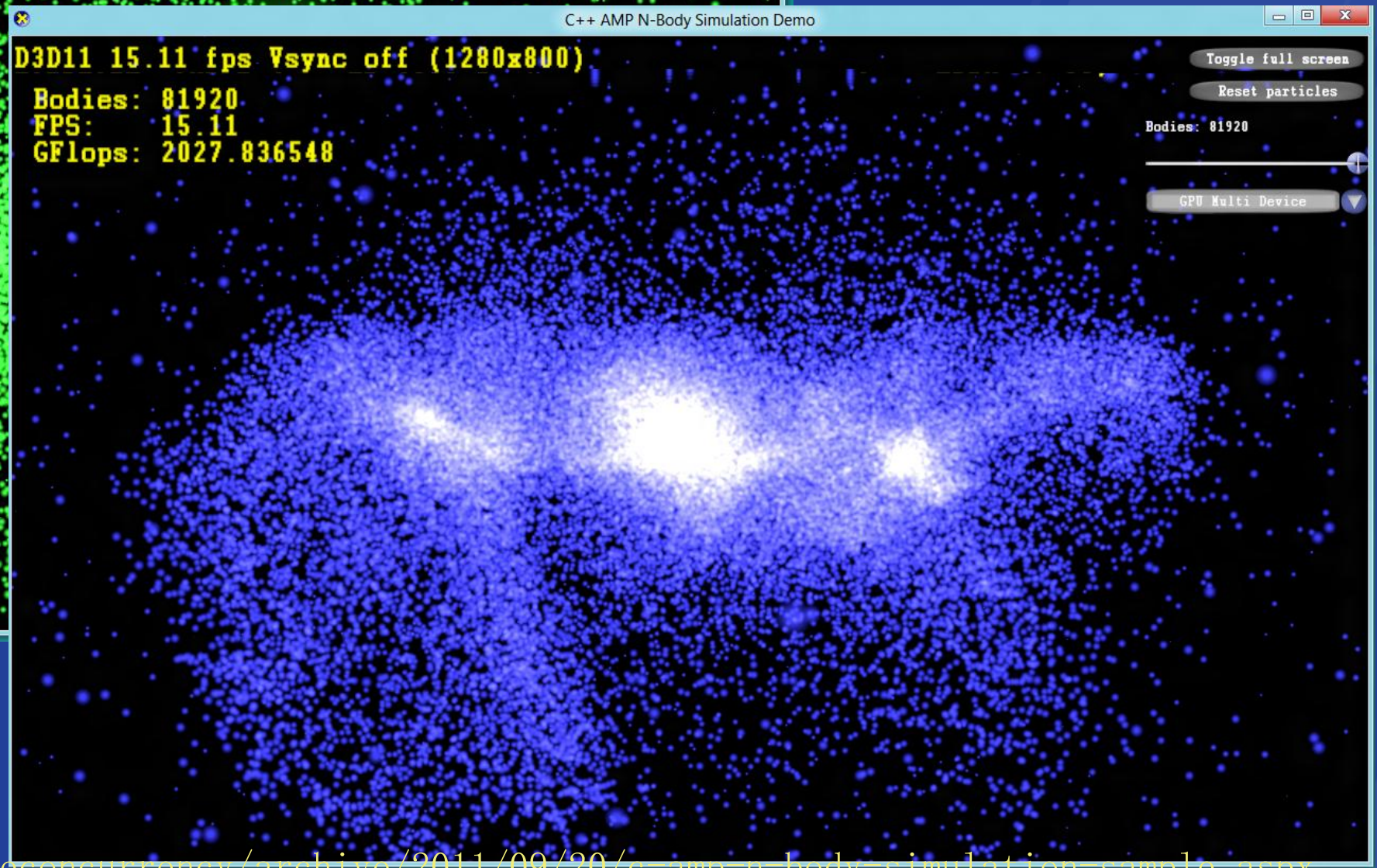
- 施凡
  - @装配脑袋
  - MSRA 微软亚洲研究

- https://github.com/ninputer
  - /AMP-Demo
- http://www.cnblogs.com/ninputer

Agenda

- Context
- Code
- IDE
- Summary





N-Body

http://blogs.msdn.com/b/nativeconcurrency/archive/2011/09/20/c-amp-n-body-simulation-sample.aspx

CPUs vs GPUs today

CPU

- Low memory bandwidth
- Higher power consumption
- Medium level of parallelism
- Shallow execution pipelines
- Random accesses
- Supports general code
- Mainstream programming

GPU

- High memory bandwidth
- Lower power consumption
- High level of parallelism
- Deep execution pipelines
- Sequential accesses
- Supports data-parallel code
- Niche programming

images source: AMD

Tomorrow…

- CPUs and GPUs coming closer together…
  - …nothing settled in this space, things still in motion…

- C++ AMP is designed as a mainstream solution not only for today, but also for tomorrow

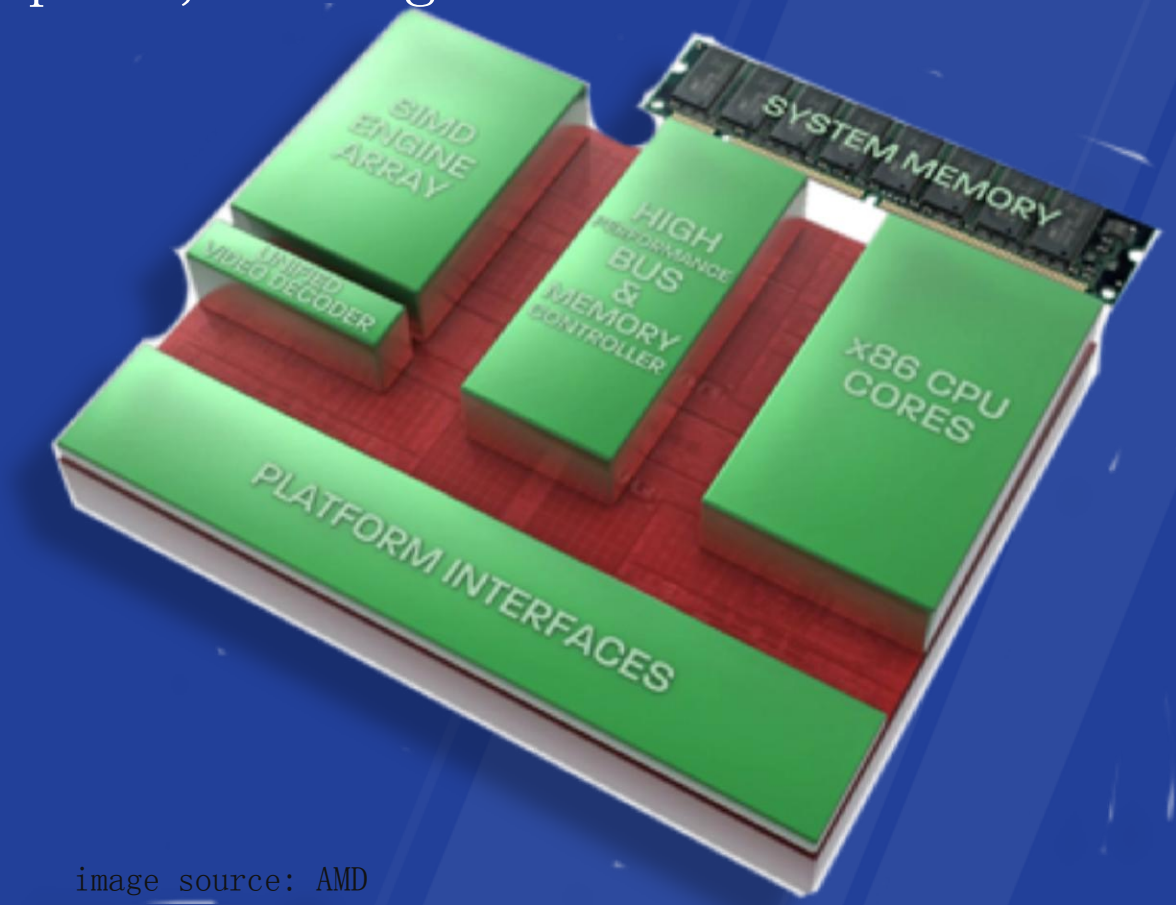
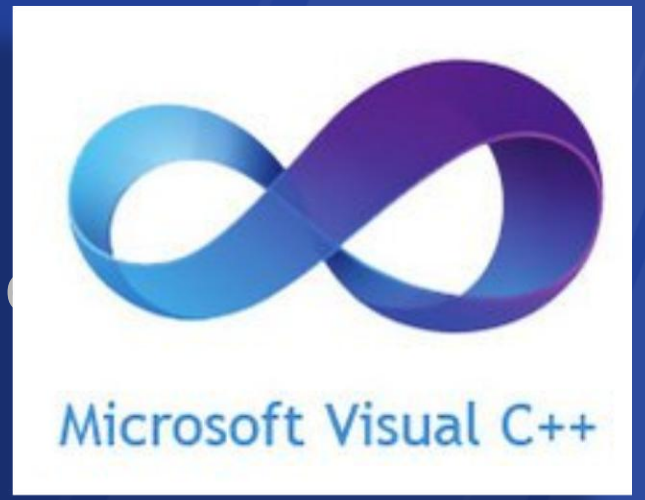


image source: AMD

C++ AMP

- Part of Visual C++
- Visual Studio integration
- STL-like library for multidimensional
- Builds on Direct3D
- An open specification



performance

productivity

portability

http://www.danielmoth.com/Blog/C-Accelerated-Massive-Parallelism.aspx

Agenda checkpoint

- Context ✔
- Code
  - Simple Model
  - Tiled Model
  - (optional) More
- IDE
- Summary

Hello World: Array Addition

```
void AddArrays(int n, int * pA, int * pB, int * pSum)
{
   for (int i=0; i<n; i++)
   {
         pSum[i] = pA[i] + pB[i];
   }
}
```

How do we take the serial code on the left that runs on the CPU and convert it to run on an accelerator like the GPU?

Hello World: Array Addition

```
void AddArrays(int n, int * pA, int * pB, int * pSum)
{




   for (int i=0; i<n; i++)


   {
         pSum[i] = pA[i] + pB[i];
   }

}
```

```
#include <amp.h>
using namespace concurrency;

void AddArrays(int n, int * pA, int * pB, int * pSum)
{
   array_view<int,1> a(n, pA);
   array_view<int,1> b(n, pB);
   array_view<int,1> sum(n, pSum);

   parallel_for_each(
      sum.extent,
      [=](index<1> i) restrict(amp)
      {
         sum[i] = a[i] + b[i];
      }
    );
}
```

Basic Elements of C++ AMP coding

```
void AddArrays(int n, int * pA, int * pB, int * pSum)
{
    array_view<int,1> a(n, pA);
    array_view<int,1> b(n, pB);
    array_view<int,1> sum(n, pSum);

    parallel_for_each(
            sum.extent,
            [=](index<1> i) restrict(amp)
            {
                sum[i] = a[i] + b[i];
            }
    );
```

parallel_for_each: execute the lambda on the accelerator once per thread

restrict(amp): tells the compiler to check that this code conforms to C++ AMP language restrictions

array_view: wraps the data to operate on the accelerator

extent: the number and shape of threads to execute the lambda

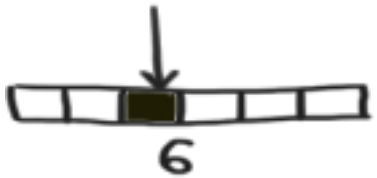
array_view variables captured and associated data copied to accelerator (on demand)

index: the thread ID that is running the lambda, used to index into data

extent<N> and index<N>

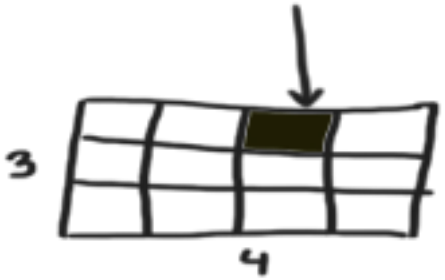
- index<N> - an N-dimensional point
- extent<N> - # of units in each dimension of an N-dim space

index<1> i(2);



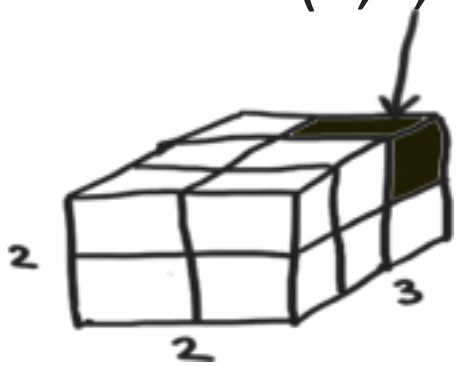
extent<1> e(6);

index<2> i(0,2);



extent<2> e(3,4);

index<3> i(2,0,1);



extent<3> e(3,2,2);

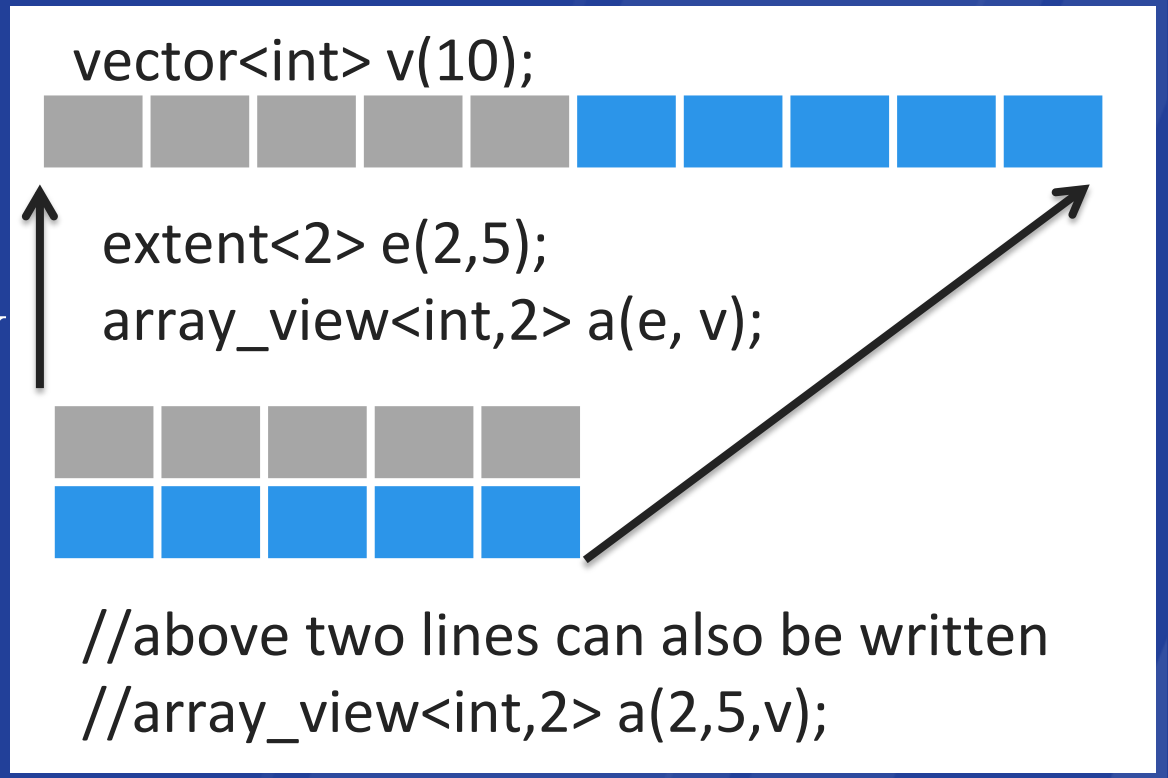
- rank N can be any number <=128

http://www.danielmoth.com/Blog/concurrencyindex-From-Amph.aspx
http://www.danielmoth.com/Blog/concurrencyextent-From-Amph.aspx

array_view<T,N>

- View on existing data on the CPU or GPU
- Dense in least significant dimension
- Of element T and rank N
- Requires extent
- Rectangular
- Access anywhere (implicit sy

```
index<2> i(1,3);

int o = a[i]; // or a[i] = 16;
//or int o = a(1, 3);
```



http://www.danielmoth.com/Blog/array-And-Arrayview-From-Amph.aspx

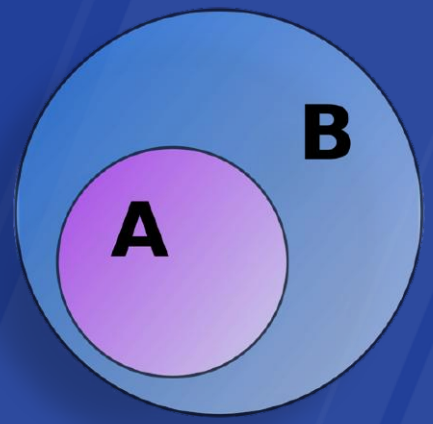
parallel_for_each

- Executes the kernel for each point in the extent
- As-if synchronous in terms of visible side-effects

```
1.  parallel_for_each(
2.      e,   //e is of type extent<N>
3.      [ ](index<N> idx) restrict(amp)
        {
            // kernel code
        }
1.  );
```

http://www.danielmoth.com/Blog/parallelforeach-From-Amph-Part-1.aspx

restrict(. . .)



- Applies to functions (including lambdas)
- *restrict(…)* informs the compiler to enforce language restrictions
  - e.g., target-specific restrictions, optimizations, special code-gen
- In 1st release we are only implementing two options
  - *cpu* - the implicit default
  - *amp* - checks that the function conforms to C++ AMP restrictions

http://blogs.msdn.com/b/nativeconcurrency/archive/2011/09/05/restrict-a-key-new-language-feature-introduced-with-c-

restrict(amp) restrictions

- Can only call other *restrict(amp)* functions
- All functions must be inlinable
- Only amp-supported types
  - int, unsigned int, float, double, bool[1]
  - structs & arrays of these types
- Pointers and References
  - Lambdas cannot capture by reference[1], nor capture pointers
  - References and single-indirection pointers supported only as local variables and function arguments

restrict(amp) restrictions

- No
  - recursion
  - 'volatile'
  - virtual functions
  - pointers to functions
  - pointers to member functions
  - pointers in structs
  - pointers to pointers
  - bitfields
- No
  - goto or labeled statements
  - throw, try, catch
  - globals or statics
  - dynamic_cast or typeid
  - asm declarations
  - varargs
  - unsupported types
    - e.g. char, short, long double

http://blogs.msdn.com/b/nativeconcurrency/archive/2011/12/19/restrict-amp-restrictions-part-0-of-n-

Example: restrict overloading

```
double cos( double d );                                  // 1a: cpu code
double cos( double d ) restrict(amp);    // 1b: amp code
double bar( double d ) restrict(cpu,amp);            // 2  : common subset of both

void some_method(array_view<double,2>& c) {
   parallel_for_each( c.extent, [=](index<2> idx) restrict(amp)
   {
     //…
     double d0 = c[idx];
     double d1 = bar(d0);       // ok, bar restrictions include amp
     double d2 = cos(d0);       // ok, chooses amp overload
     //…
   });
}
```

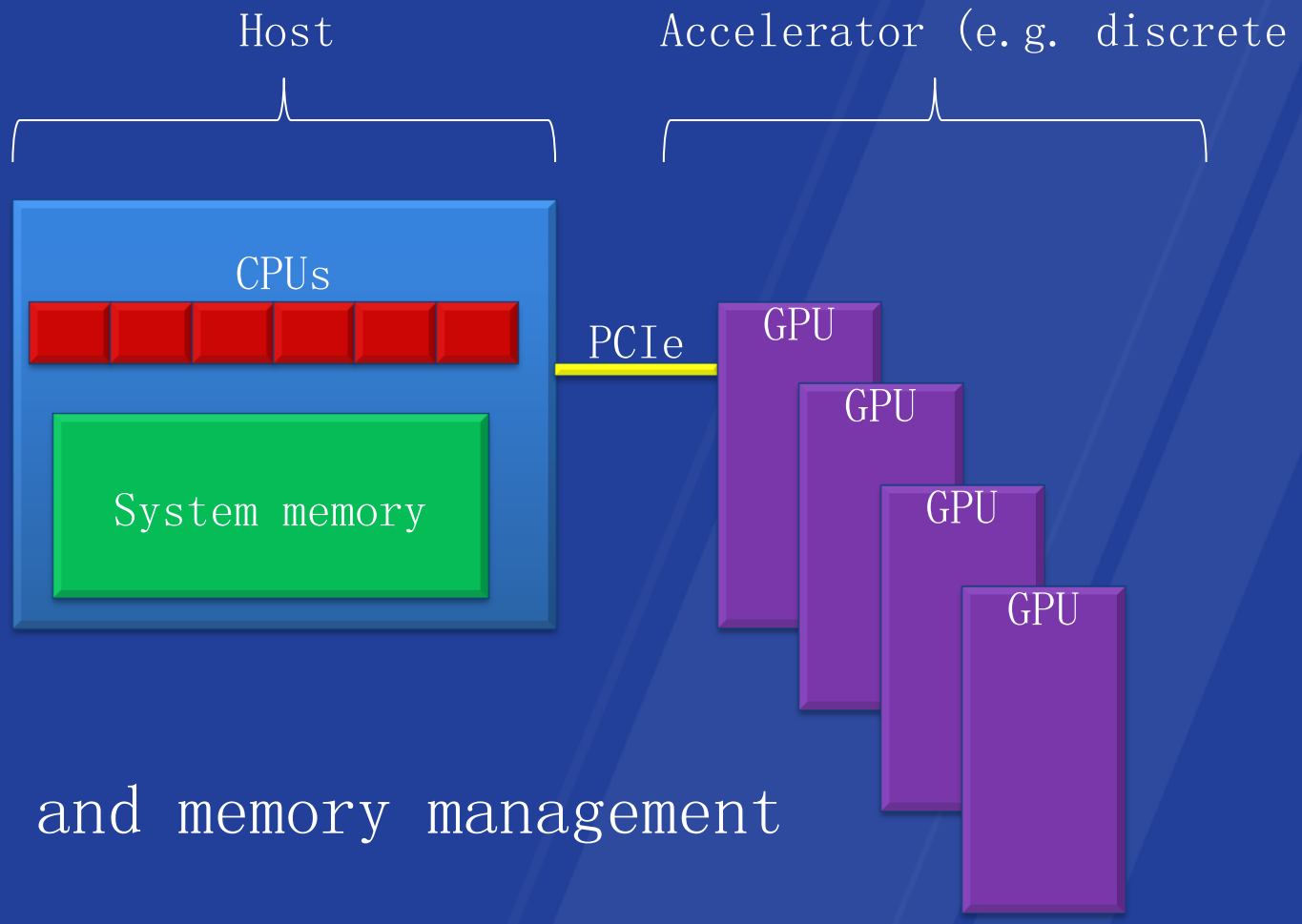
Example: Matrix Multiplication

```
void MatrixMultiplySerial( vector<float>& vC,
    const vector<float>& vA,
    const vector<float>& vB, int M, int N, int W )
{




   for (int row = 0; row < M; row++) {
     for (int col = 0; col < N; col++){
       float sum = 0.0f;
       for(int i = 0; i < W; i++)
         sum += vA[row * W + i] * vB[i * N + col];
       vC[row * N + col] = sum;
     }
   }
}
```

```
void MatrixMultiplyAMP( vector<float>& vC,
    const vector<float>& vA,
    const vector<float>& vB, int M, int N, int W )
{
   array_view<const float,2> a(M,W,vA),b(W,N,vB);
   array_view<float,2> c(M,N,vC);
   c.discard_data();
   parallel_for_each(c.extent,
       [=](index<2> idx) restrict(amp) {
           int row = idx[0]; int col = idx[1];
           float sum = 0.0f;
           for(int i = 0; i < W; i++)
             sum += a(row, i) * b(i, col);
           c[idx] = sum;
       }
     );
}
```

accelerator, accelerator_view

- accelerator
  - e.g. DX11 GPU
  - e.g. WARP, REF
  - e.g. CPU



- accelerator_view
  - a context for scheduling and memory management

http://www.danielmoth.com/Blog/concurrencyaccelerator.aspx
http://www.danielmoth.com/Blog/concurrencyacceleratorview.aspx

Example: accelerator

accelerator
Class

- ~accelerator()
- accelerator()
- accelerator(const accelerator& _Other)
- accelerator(const wstring& _Device_path)
- cpu_accelerator : const wchar_t[]
- create_view(queuing_mode qmode) : accelerator_view
- dedicated_memory : size_t
- default_accelerator : const wchar_t[]
- default_view : accelerator_view
- description : wstring
- device_path : wstring
- direct3d_ref : const wchar_t[]
- direct3d_warp : const wchar_t[]
- get_all() : vector<accelerator>
- has_display : bool
- is_debug : bool
- is_emulated : bool
- set_default(wstring _Path) : bool
- supports_double_precision : bool
- version : unsigned int

accelerator_view
Class

- ~accelerator_view()
- accelerator : accelerator
- accelerator_view(const accelerator_view& _Other)
- create_marker() : shared_future<void>
- flush() : void
- is_debug : bool
- queuing_mode : queuing_mode
- version : unsigned int
- wait() : void

```
// enumerate all accelerators
vector<accelerator> accs = accelerator::get_all();

// choose one based on your criteria
accelerator acc = accs[0];

// launch a kernel on it
parallel_for_each(acc.default_view, my_extent, [=]…);
```

array<T, N>

- Multi-dimensional array of rank N with element T
- Container whose storage lives on a specific accelerator
- Capture by reference [&] in the lambda
- Explicit copy
- Nearly identical interface to array_view<T, N>

```
vector<int> v(8 * 12);
extent<2> e(8,12);
accelerator acc = …
array<int,2> a(e, acc.default_view);
copy_async(v.begin(), v.end(), a);
```

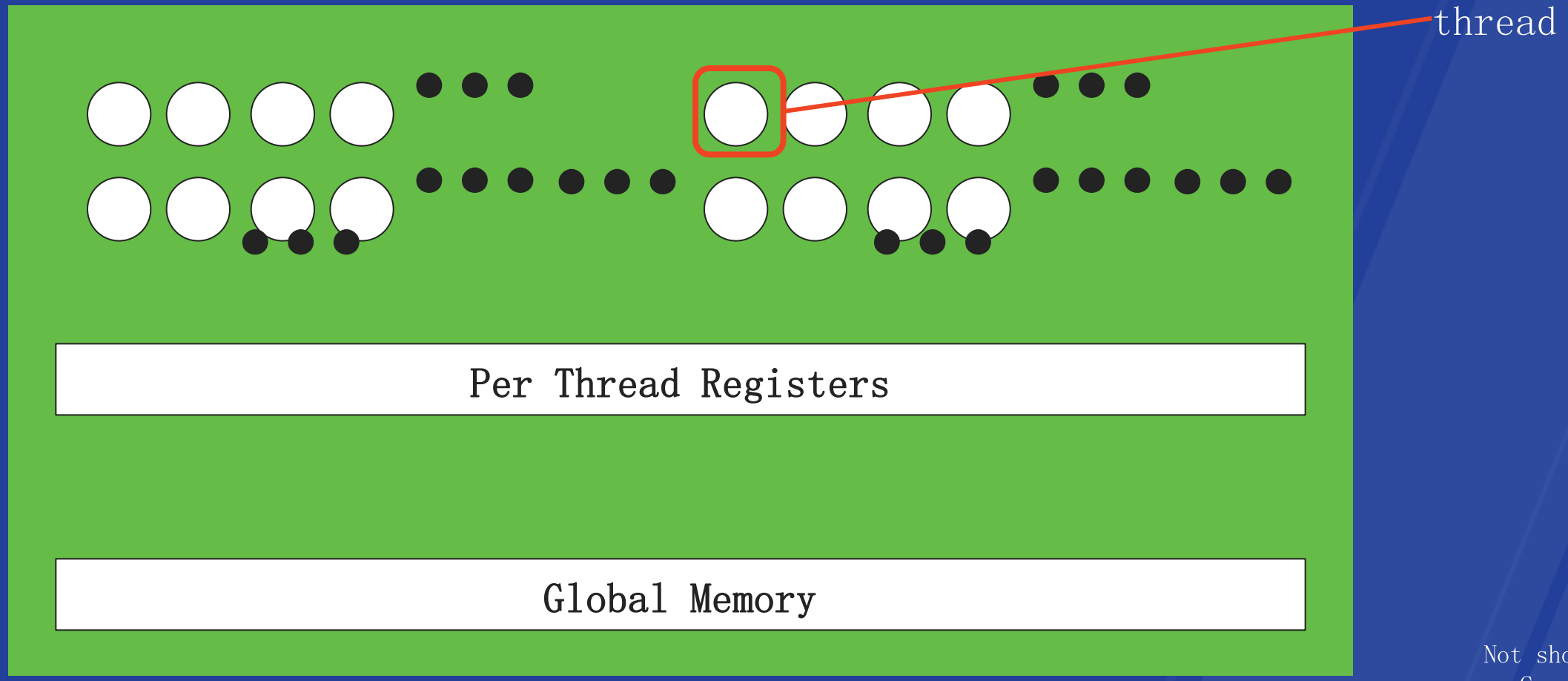
```
parallel_for_each(e, [&](index<2> idx) restrict(amp)
{
    a[idx] += 1;
});
copy(a, v.begin());
```

http://www.danielmoth.com/Blog/array-And-Arrayview-From-Amph.aspx

C++ AMP at a Glance (so far)

- restrict(amp, cpu)
- parallel_for_each
- class accelerator_view
- class accelerator
- class extent<N>
- class index<N>
- class array_view<T,N>
- class array<T,N>

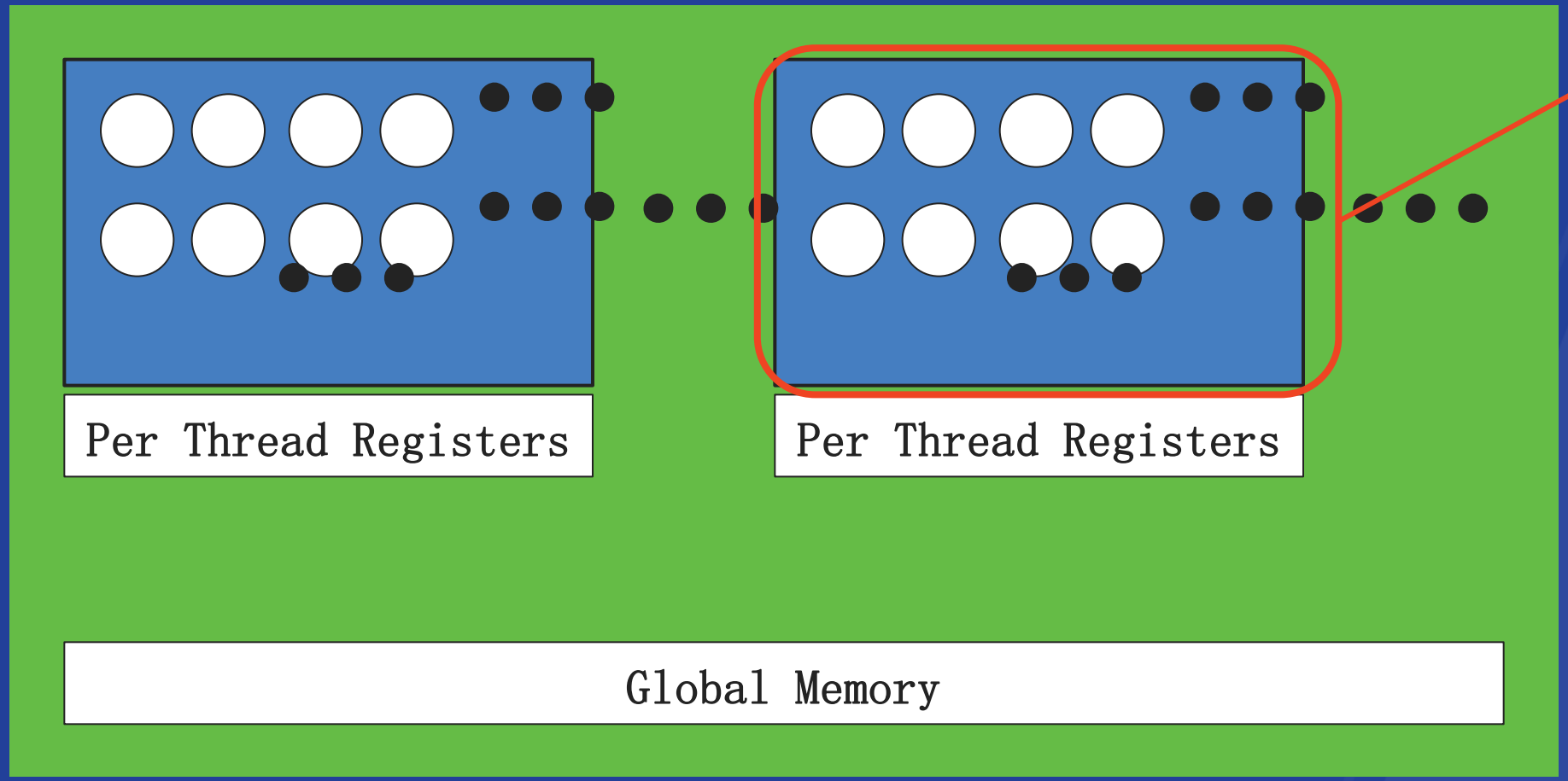
Hardware from a Developer Perspective



Not showing:

- Constant memory
- Memory controllers
- Schedulers
- Other caches
- Multi-GPU case

Hardware from a Developer Perspective



Not showing:

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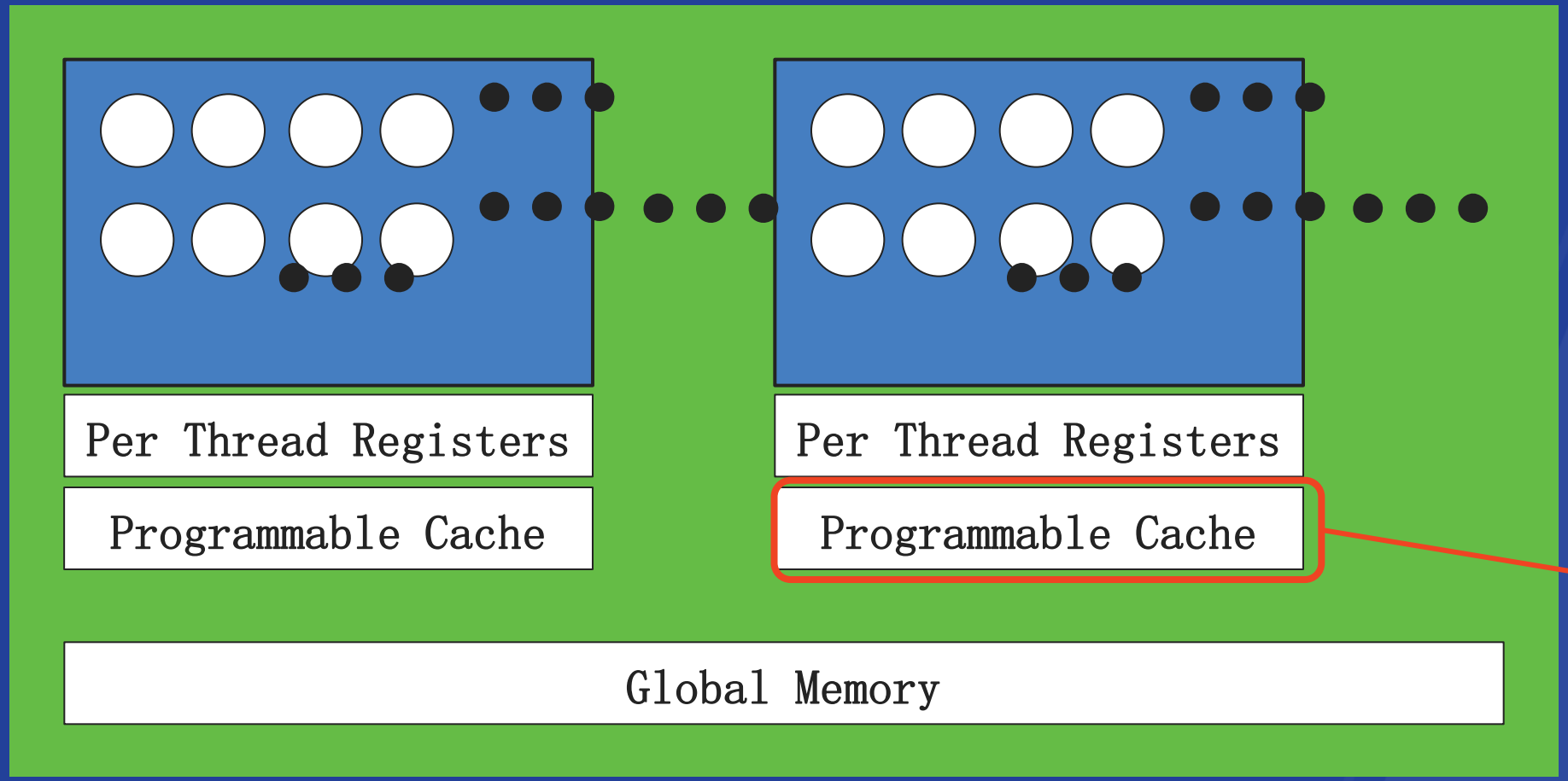
Hardware from a Developer Perspective



tile_static variables shared by threads in the same tile

Not showing:

- Constant memory
- Memory controllers
- Schedulers
- Other caches
- Multi-GPU case

parallel_for_each: tiled overload

- Schedule threads in tiles
  - Gain ability to use tile static

```
array_view<int,1> data(12, my_data);

parallel_for_each(data.extent,
   [=] (index<1> idx) restrict(amp)
   { … });

parallel_for_each(data.extent.tile<6>(),
   [=] (tiled_index<6> t_idx) restrict(amp)
   { … });
```

- parallel_for_each overload for tiles accepts
  - tiled_extent<D0> or tiled_extent<D0, D1> or tiled_extent<D0, D1, D2>
  - a lambda which accepts
    - tiled_index<D0> or tiled_index<D0, D1> or tiled_index<D0, D1, D2>

tiled_extent (from extent)

extent<1> e(12);

0	1	2	3	4	5	6	7	8	9	10	11

tiled_extent<6> t_e = e.**tile<6>()**;

0	1	2	3	4	5	6	7	8	9	10	11

extent<2> ee(2, 6);

0,0	0,1	0,2	0,3	0,4	0,5
1,0	1,1	1,2	1,3	1,4	1,5

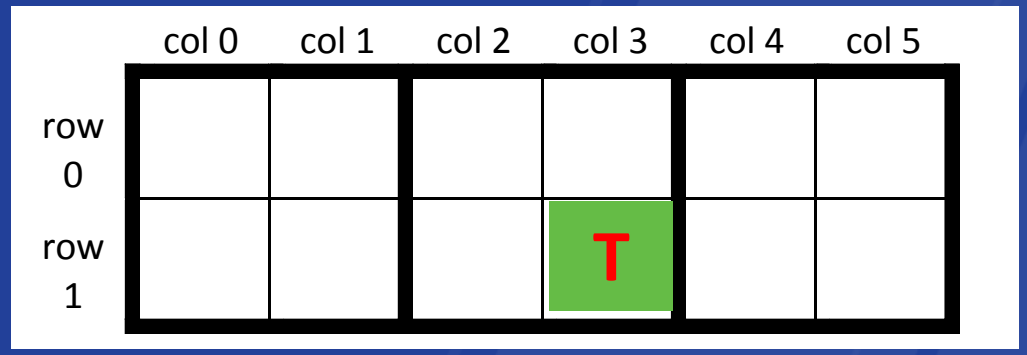
tiled_extent<2, 2> t_ee = ee.**tile<2, 2>()**;

0,0	0,1	0,2	0,3	0,4	0,5
1,0	1,1	1,2	1,3	1,4	1,5

tiled_index

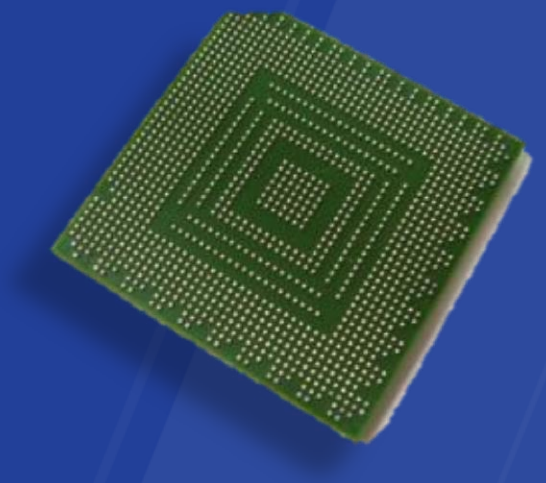
- Given

```
array_view<int,2> data(2, 6, p_my_data);
parallel_for_each(
    data.extent.tile<2,2>(),
    [=] (tiled_index<2,2> t_idx)… { … });
```



- When the lambda is executed T
  - t_idx.global // index<2> (1,3)
  - t_idx.local // index<2> (1,1)
  - t_idx.tile // index<2> (0,1)
  - t_idx.tile_origin // index<2> (0,2)

tile_static



- The tile_static storage class
  - Second addition to the C++ language
  - Reflects hardware memory hierarchy

- Within the tiled parallel_for_each lambda we can use
  - tile_static for local variables
    - indicates that the variable is allocated in fast cache memory
      - i.e. shared by each thread in a tile of threads
    - only applicable in restrict(amp) functions

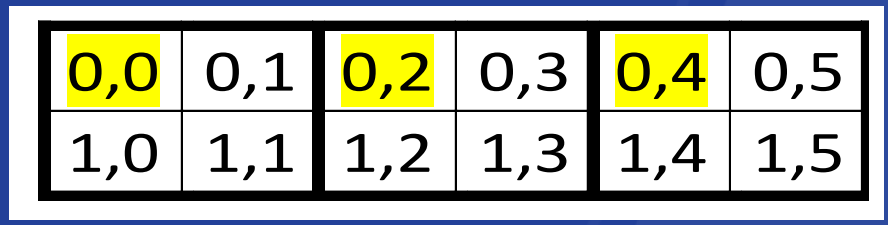
http://blogs.msdn.com/b/nativeconcurrency/archive/2012/01/11/restrict-amp-restrictions-part-10-of-n-tile-static.aspx

tile_static storage class

0,0	0,1	0,2	0,3	0,4	0,5
1,0	1,1	1,2	1,3	1,4	1,5

```
1   static const int TS = 2;
2   array_view<int, 2> av(2, 6, my_vector);
3   parallel_for_each(av.extent.tile<TS,TS>(),
    [=](tiled_index<TS,TS> t_idx) restrict(amp)
4   {
5
6
7
8                    imagine the code here
9
10
11
12  });
13  int sum = av(0,0) + av(0,2) + av(0,4); //the three tile_origins
```

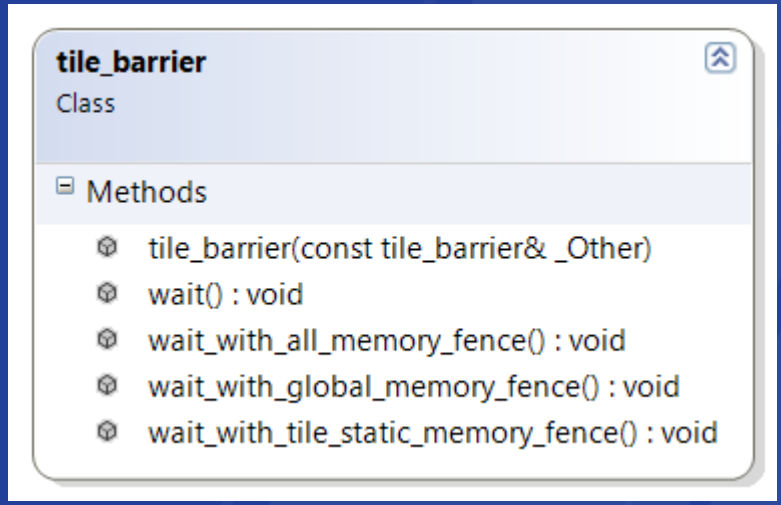
tile_static storage class




```
1   static const int TS = 2;
2   array_view<int, 2> av(2, 6, my_vector);
3   parallel_for_each(av.extent.tile<TS,TS>(),
    [=](tiled_index<TS,TS> t_idx) restrict(amp)
4   {
5       tile_static int t[TS][TS];
6       t[t_idx.local[0]][t_idx.local[1]] = av[t_idx.global];
7
8       if (t_idx.local == index<2>(0,0)) {
9          int temp = t[0][0] + t[0][1] + t[1][0] + t[1][1];
10         av[t_idx.tile_origin] = temp;
11      }
12  });
13  int sum = av(0,0) + av(0,2) + av(0,4); //the three tile_origins
```

tile_barrier

- class tile_barrier
  - synchronize all threads within a tile
  - e.g. t_idx.barrier.wait();



- Plus
  - Fences (without barriers)
    - all_memory_fence, global_memory_fence, tile_static_memory_fence
  - Atomics
    - atomic_exchange, atomic_compare_exchange, atomic_fetch_*

http://blogs.msdn.com/b/nativeconcurrency/archive/2011/12/24/tile-barrier-in-c-amp.aspx
http://blogs.msdn.com/b/nativeconcurrency/archive/2012/01/04/c-amp-s-atomic-operations.aspx

tile_barrier class

0,0	0,1	0,2	0,3	0,4	0,5
1,0	1,1	1,2	1,3	1,4	1,5

```
1   static const int TS = 2;
2   array_view<int, 2> av(2, 6, my_vector);
3   parallel_for_each(av.extent.tile<TS,TS>(),
    [=](tiled_index<TS,TS> t_idx) restrict(amp)
4   {
5       tile_static int t[TS][TS];
6       t[t_idx.local[0]][t_idx.local[1]] = av[t_idx.global];
7       t_idx.barrier.wait();
8       if (t_idx.local == index<2>(0,0)) {
9          int temp = t[0][0] + t[0][1] + t[1][0] + t[1][1];
10         av[t_idx.tile_origin] = temp;
11      }
12  });
13  int sum = av(0,0) + av(0,2) + av(0,4); //the three tile_origins
```

Example: Matrix Multiplication (tiled) -

```
void MatrixMultSimple(vector<float>& vC, const
vector<float>& vA, const vector<float>& vB, int M, int N,
int W )
{

   array_view<const float,2> a(M, W, vA), b(W, N, vB);
   array_view<float,2> c(M,N,vC);  c.discard_data();
   parallel_for_each(c.extent,
      [=] (index<2> idx) restrict(amp)
      {
         int row = idx[0];
         int col = idx[1];

         float sum = 0.0f;
         for(int k = 0; k < W; k++)
            sum += a(row, k) * b(k, col);

         c[idx] = sum;
      } );
}
```

```
void MatrixMultTiled(vector<float>& vC, const
vector<float>& vA, const vector<float>& vB, int M, int
N, int W )
{
   static const int TS = 16;
   array_view<const float,2> a(M, W, vA), b(W, N, vB);
   array_view<float,2> c(M,N,vC);  c.discard_data();
   parallel_for_each(c.extent.tile< TS, TS >(),
      [=] (tiled_index< TS, TS> t_idx) restrict(amp)
      {
         int row = t_idx.global[0];
         int col =   t_idx.global[1];

         float sum = 0.0f;
         for(int k = 0; k < W; k++)
            sum += a(row, k) * b(k, col);

         c[t_idx.global] = sum;
      } );
}
```

Example: Matrix Multiplication (tiled) -

```
void MatrixMultSimple(vector<float>& vC, const vector<float>& vA,
const vector<float>& vB, int M, int N, int W )
{
   static const int TS = 16;
   array_view<const float,2> a(M, W, vA), b(W, N, vB);
   array_view<float,2> c(M,N,vC);  c.discard_data();
   parallel_for_each(c.extent.tile< TS, TS >(),
      [=] (tiled_index< TS, TS> t_idx) restrict(amp)  {
         int row = t_idx.global[0]; int col = t_idx.global[1];

         float sum = 0.0f;

         for(int k = 0; k < W; k++)
            sum += a(row, k) * b(k, col);

         c[t_idx.global] = sum;
      } );
}
```

```
void MatrixMultTiled(vector<float>& vC, const vector<float>& vA,
const vector<float>& vB, int M, int N, int W )
{
   static const int TS = 16;
   array_view<const float,2> a(M, W, vA), b(W, N, vB);
   array_view<float,2> c(M,N,vC);  c.discard_data();
   parallel_for_each(c.extent.tile< TS, TS >(),
      [=] (tiled  index< TS, TS> t  idx) restrict(amp)  {

imagine the code here

         c[t_idx.global] = sum;
      } );
}
```

Example: Matrix Multiplication (tiled) -

```
void MatrixMultSimple(vector<float>& vC, const vector<float>& vA,
const vector<float>& vB, int M, int N, int W )
{
   static const int TS = 16;
   array_view<const float,2> a(M, W, vA), b(W, N, vB);
   array_view<float,2> c(M,N,vC);  c.discard_data();
   parallel_for_each(c.extent.tile< TS, TS >(),
      [=] (tiled_index< TS, TS> t_idx) restrict(amp)  {
         int row = t_idx.global[0]; int col = t_idx.global[1];

         float sum = 0.0f;









         for(int k = 0; k < W; k++)
            sum += a(row, k) * b(k, col);



         c[t_idx.global] = sum;
      } );
}
```

```
void MatrixMultTiled(vector<float>& vC, const vector<float>& vA,
const vector<float>& vB, int M, int N, int W )
{
   static const int TS = 16;
   array_view<const float,2> a(M, W, vA), b(W, N, vB);
   array_view<float,2> c(M,N,vC);  c.discard_data();
   parallel_for_each(c.extent.tile< TS, TS >(),
      [=] (tiled_index< TS, TS> t_idx) restrict(amp)  {
         int row = t_idx.local[0]; int col = t_idx.local[1];
         tile_static float locA[TS][TS], locB[TS][TS];
         float sum = 0.0f;
         for (int i = 0; i < W; i += TS) {
            locA[row][col] = a(t_idx.global[0], col + i);
            locB[row][col] = b(row + i, t_idx.global[1]);
            t_idx.barrier.wait();

            for (int k = 0; k < TS; k++)
               sum += locA[row][k] * locB[k][col];
            t_idx.barrier.wait();
          }
         c[t_idx.global] = sum;
      } );
}
```

Phase 1

Phase 2

C++ AMP at a Glance

- restrict(amp, cpu)
- parallel_for_each
- class accelerator_view
- class accelerator
- class extent<N>
- class index<N>
- class array_view<T,N>
- class array<T,N>
- tile_static storage class
- class tiled_extent< , , >
- class tiled_index< , , >
- class tile_barrier

Error handling

- Some APIs can throw
  - e.g. parallel_for_each

- Exceptions
  - concurrency::runtime_exception
  - concurrency::out_of_memory
  - concurrency::unsupported_feature
  - concurrency::invalid_compute_domain
  - concurrency::accelerator_view_removed

```
/* Trying to use REF emulator on a
machine that does not have it installed,
throws runtime_exception */
 try
 {
   accelerator a(accelerator::direct3d_ref);
 }
 catch(runtime_exception& ex)
{
  std::cout << ex.what() << std::endl;
}
```

http://blogs.msdn.com/b/nativeconcurrency/archive/2012/01/27/c-amp-runtime-exceptions.aspx

<amp_math.h>

- concurrency::fast_math
  - Wrap HLSL intrinsics
  - 35 functions
  - Single-precision only
  - Sacrifice accuracy for sp
- concurrency::precise_mat
  - 68 functions
  - Require full double preci
    - even for single precision

```
1.  #include <amp.h>
2.  #include <amp_math.h>
3.  using namespace concurrency;
4.  using namespace concurrency::fast_math;
    // using namespace concurrency::precise_math;
5.  int main() {
6.      float a = 2.2f, b = 3.5f;
7.      float result = pow(a,b);
8.      std::vector<float> v(1);
9.      array_view<float> av(1,v);
10.     parallel_for_each(av.extent, [=](index<1> idx)
    restrict(amp)
11.     {
12.         av[idx] = pow(a,b);
13.     });
14. }
```

http://blogs.msdn.com/b/nativeconcurrency/archive/2012/02/08/math-library-for-c-amp.aspx

<amp_graphics.h>, concurrency::graphics

- norm/unorm scalar type
- Short vector types (int_3, float_4, norm_2, etc.)
  - Swizzle expressions: myvec.yzx = int_3(1, 2, 3);

- Textures – efficient access to 1d, 2d
  - Element type is scalar or SVT of rank 1,
  - DX limitations apply
  - Different encodings supported
  - Interop with DX texture resources

http://blogs.msdn.com/b/nativeconcurrency/archive/2012/01/25/concurrency-graphics-in-c-amp.aspx

DirectX Integration, concurrency::direct3d

- Weave C++ AMP code and data with DX-based applications

C++ AMP type	DirectX type	C++ AMP interop API
array	ID3D11Buffer	*get_buffer, make_array
texture	ID3D11Texture1D/2D/3D	*get_texture, make_texture
accelerator_view	ID3D11Device	*get_device, create_accelerator_view

- Example: **n-body simulation**
  - Populates an array of particular positions using parallel_for_each
  - Then read it in a vertex shader

http://blogs.msdn.com/b/nativeconcurrency/archive/2012/02/24/interoperability-between-direct-3d-and-c-amp.aspx
http://blogs.msdn.com/b/nativeconcurrency/archive/2012/02/24/direct3d-namespace-and-hlsl-intrinsics-in-c-amp.aspx

Agenda checkpoint

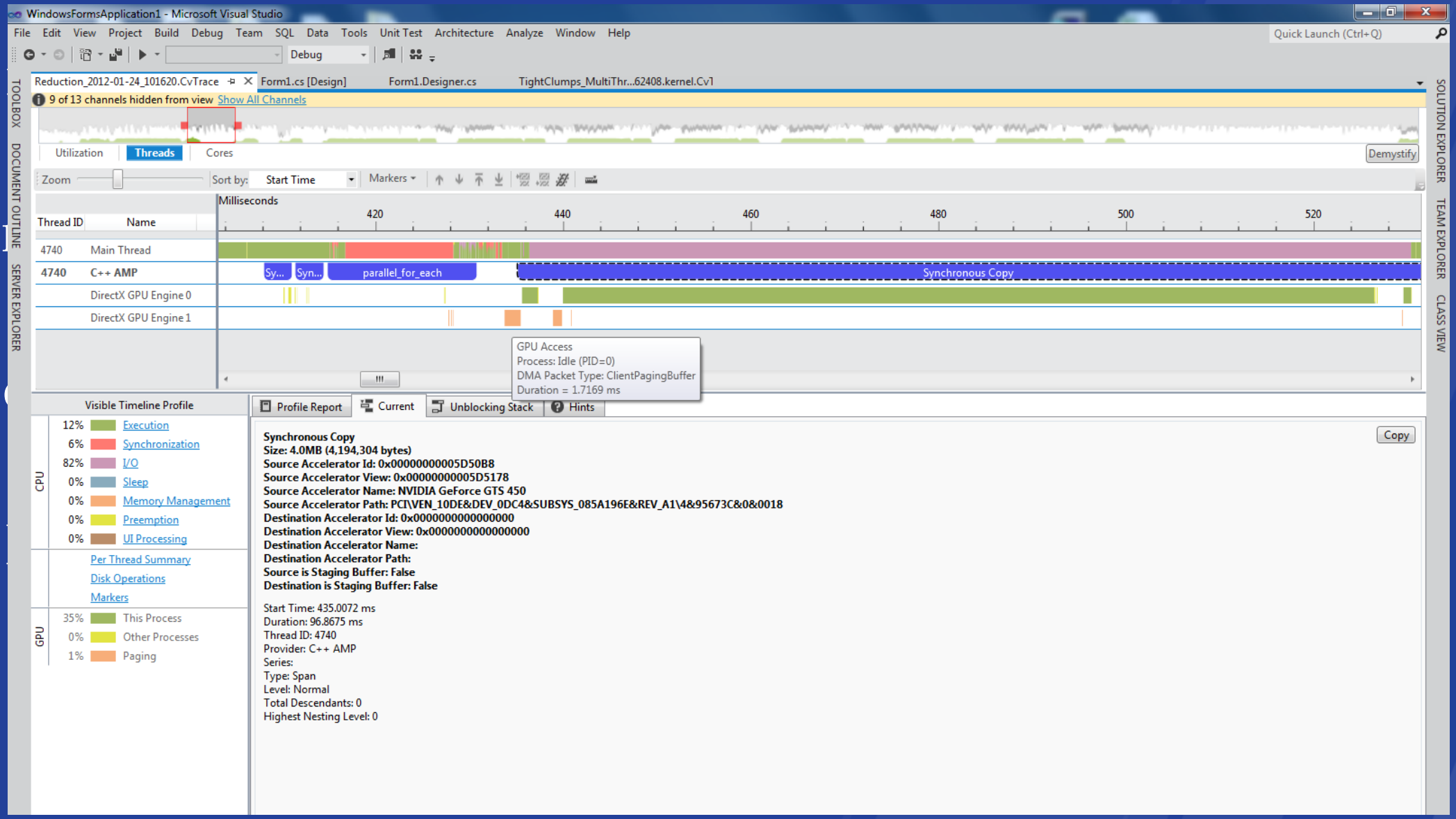
- Context
- Code
- IDE
- Summary

Visual Studio 2012

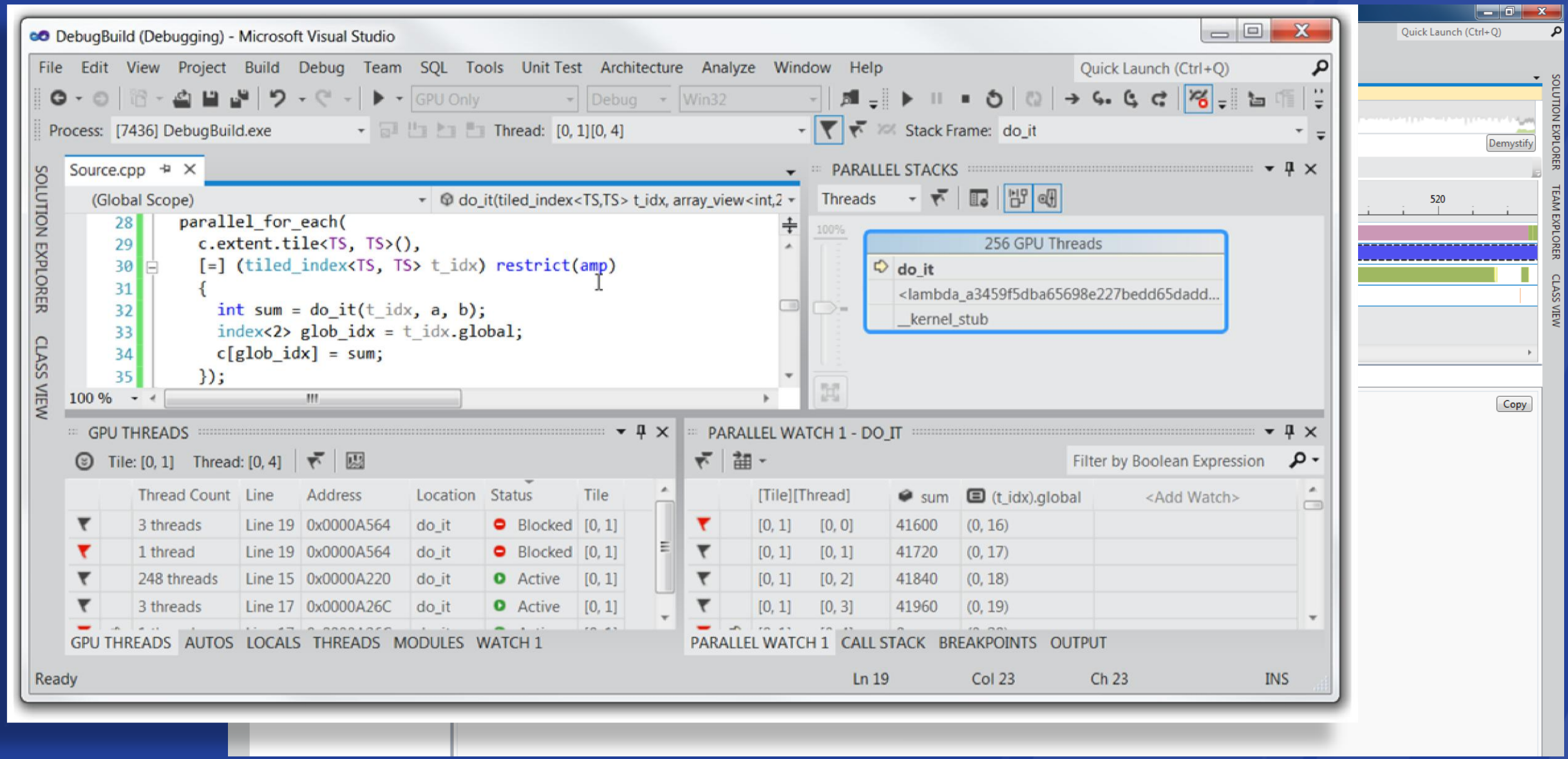
- Organize
- Edit
- Design
- Build
- Browse
- Debug
- Profile

Visual Studio 2012

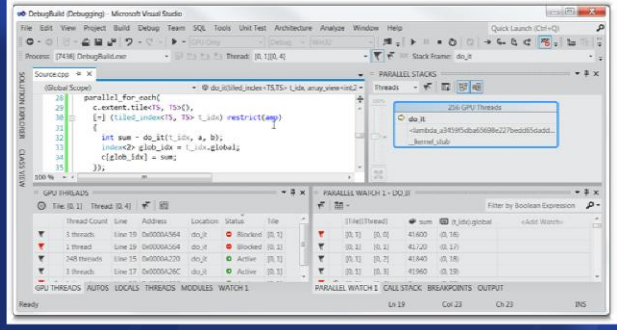
- Organ
- Edit
- Design
- Build
- Brows
- Debug
- Profi



Visual Studio 2012



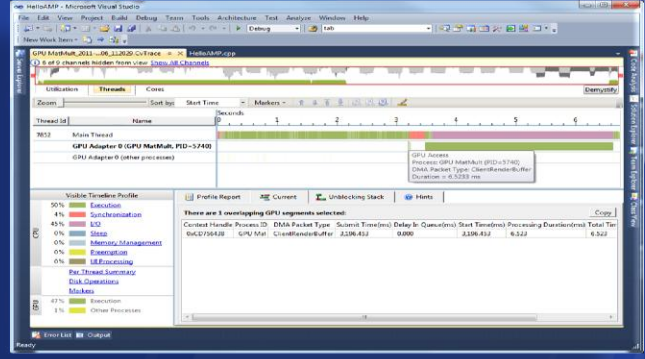
C++ AMP Parallel Debugger



- Well known Visual Studio debugging features
  - Launch (incl. remote), Attach, Break, Stepping, Breakpoints, DataTips
  - Toolwindows
    - Processes, Debug Output, Modules, Disassembly, Call Stack, Memory, Registers, Locals, Watch, Quick Watch
- New features (for both CPU and GPU)
  - Parallel Stacks window, Parallel Watch window, Barrier
- New GPU-specific
  - Emulator, GPU Threads window, race detection
- concurrency::direct3d_printf, _errorf, _abort

http://channel9.msdn.com/Events/BUILD/BUILD2011/TOOL-802T *(51:54-59:16)*

Concurrency Visualizer for GPU



- Direct3D-centric
  - Supports any library/programming model built on it
  - C++ AMP specific events
- Integrated GPU and CPU view
- Goal is to analyze high-level performance metrics
  - Memory copy overheads
  - Synchronization overheads across CPU/GPU
  - GPU activity and contention with other processes

http://blogs.msdn.com/b/nativeconcurrency/archive/2012/03/09/analyzing-c-amp-code-with-the-concurrency-visualizer.aspx

Agenda checkpoint

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Learn C++ AMP

- book http://www.gregcons.com/cppamp/
- training http://www.acceleware.com/cpp-amp-training
- videos http://channel9.msdn.com/Tags/c++-accelerated-massive-parallelism
- articles http://blogs.msdn.com/b/nativeconcurrency/archive/2012/04/05/c-amp-articles-in-msdn-magazine-april-issue.aspx
- samples http://blogs.msdn.com/b/nativeconcurrency/archive/2012/01/30/c-amp-sample-projects-for-download.aspx
- guides http://blogs.msdn.com/b/nativeconcurrency/archive/2012/04/11/c-amp-for-the-cuda-programmer.aspx
- spec http://blogs.msdn.com/b/nativeconcurrency/archive/2012/02/03/c-amp-open-spec-published.aspx
- forum http://social.msdn.microsoft.com/Forums/en/parallelcppnative/threads

http://blogs.msdn.com/nativeconcurrency/

Summary

- Democratization of parallel hardware programmability
  - Performance for the mainstream
  - Hardware abstraction platform
  - High-level abstractions in modern C++ (*not* C)
  - Future proof, minimal, data-parallel API
  - An open specification
  - State-of-the-art Visual Studio IDE

http://blogs.msdn.com/b/nativeconcurrency/archive/2012/02/03/c-amp-open-spec-published.aspx

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